

DATA ANALYSES OF ONBOARD DISTRIBUTION NETWORK

Paul BURLACU¹
Mircea TARHOACA²

¹ Lecturer, PhD, "Mircea cel Batran" Naval Academy,

² PhD student, Eng., "Mircea cel Batran" Naval Academy

Abstract: This paper presents a real-time software implementation for a vessel network supply data acquisition system. The software that are used is realized in LabVIEW and the hardware target is a NI-USB-6221 Data Acquisition System from National Instruments.

Introduction

Onboard of a ship the voltage values are different starting with light, power supply and emergency supply so this is the reason of using transformers. All of this are covered by Naval Registers. For navy ships using the STANAG 1008 Register is compulsory, so this study is in total agreement of this.

Nowadays, ensuring the quality parameters for a ship network is a core requirements for Naval Registers, due to deployment of a large number of electrical equipment. Taking all the above in consideration, this paper presents a real-time software implementation for a vessel network supply data acquisition system. The entire work carried-out for hardware equipment that consists in NI-USB-6221 Data Acquisition System was done using a quite new technology for digital systems provided by National Instruments which allowed us to monitor the main characteristics of the ship supply network. Beside the default graphical characteristics that were obtained a description of the STANAG 1008 Register was presented in order to implement the Data Acquisition System.

NI measurement device and application software were configured for acquiring and sending data to device. The graphs were recorded so we gathered all information for this study.

Sensors and transducers detect physical phenomena. Signal conditioning components condition physical phenomena so that the measurement device can receive the data. The computer receives the data through the measurement device. Software controls the measurement system, telling the measurement device when and from which channels to acquire data. Software also takes the raw data, analyzes it, and presented it in a graphic mode and file report that can help us to understand the phenomena.

1. Purpose of measurements

The purpose of measurements performed in the on-shore power station is to determine the quality parameters of the provided energy (substation and converter - SC) in compliance with 1008 STANAG standard requirements

2. Supporting documents

In order to determine, define, calculate and measure the technical parameters to be met by the electrical power systems on board warships the requirements of STANAG 1008 NAV (EDITION) - Characteristics of shipboard electrical power systems in the north of warships atlantic navies Treaty have been used.

Compliance with the technical requirements of these standards ensures functional compatibility between the electrical power source, which is the ship's power system

Conclusions

In no load running and according to the outcomes in table 1, it may be concluded that the quality requirements for the energy supply in compliance with STANAG 1008 have been met.

Bibliography

- [1] Francis A. Okou, Ouassima Akhrif, Louis-A. Dessaint, *A Robust Nonlinear Multivariable Controller for Multimachine Power Systems*, Proceedings of the American Control Conference Denver, Colorado, 2003
- [2] Francis A. Okou, Ouassima Akhrif, Louis-A. Dessaint, Roger Champagne, *Application of a Multivariable Feedback Linearization Scheme for Rotor Angle Stability and Voltage Regulation of Power Systems*, IEEE Transactions on Power Systems, vol.14, no.2, 1999
- [3] Ricardo S. Sanchez-Pena, Mario Sznajer, *Robust Systems, Theory and Applications*, John Wiley & Sons, 1998
- [4] John Doyle, Bruce Francis, Allen Tannenbaum, *Feedback Control Theory*, Macmillan Publishing, 1990
- [5] *Robust Control Toolbox for use with Matlab*, MathWorks 2005
- [6] Jeffrey Spooner, Manfredi Maggiore, Raul Ordonez, Kevin Passino, *Stable Adaptive Control and Estimation for Nonlinear Systems*, John Wiley & Sons, 2002
- [7] M.S. Ghazizadeh, F.M. Hughes, *A Generator Transfer Function Regulator for Improved Excitation Control*, IEEE Transactions on Power Systems, vol.13, no.2, 1998

(including generators and distribution systems to the consumer), and the electrical consumers.

3. The importance of parameter measurement in the power station

Electrical parameter measurement in the distribution network primarily aims to check their compliance with the quality standards required by STANAG 1008 and the designer.

4. Technical report

The electric power distribution is achieved by help of two independent null insulated distributions. The measurements were performed on first semester of 2015, and lasted one hour. The structure of the gauging and data processing system was as follows:

- R, S, T bars were chosen as measurement reference points of distribution ...
- 3 rapid voltage converters and 1 frequency converter.
- gauging and calculation portable system Lenovo G510, with data acquisition card DAQCardNI-USB-6221 – National Instruments SUA, with 16 channels which ensure 16 bit analog/digital conversion at a sampling frequency of 4.2 KS/s.
- voltage signal acquisition has been performed for 60 mins for #1 converter and for 24 mins for #2 converter and instantaneous values of voltage and frequency that were simultaneous on the three phases were recorded.
- data acquisition and processing software LabVIEW 2013 and application software designed for the acquisition platform.

The measurements were performed with no-load run sources, according to the situation on the day the measurements were performed.

5. Outcomes

Electric parameters defined as per STANAG 1008 were taken into consideration.

Calculation algorithms are in accordance with the definitions and formulas within this standard.

Data acquisitions and parameter calculation were performed with the help of the application software.

The outcomes are included in Table 1. Annexes 1.1 and 1.2 show graphs of the analysed parameters.

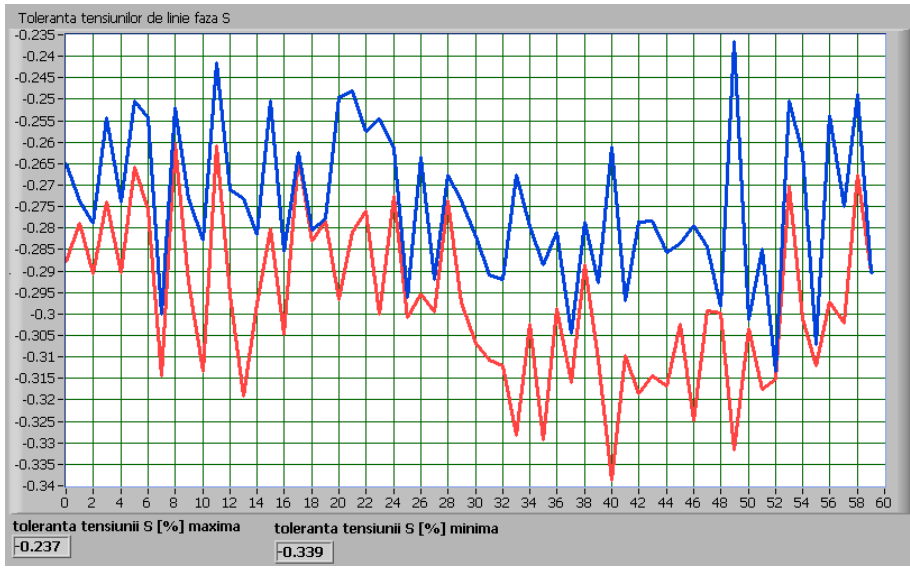
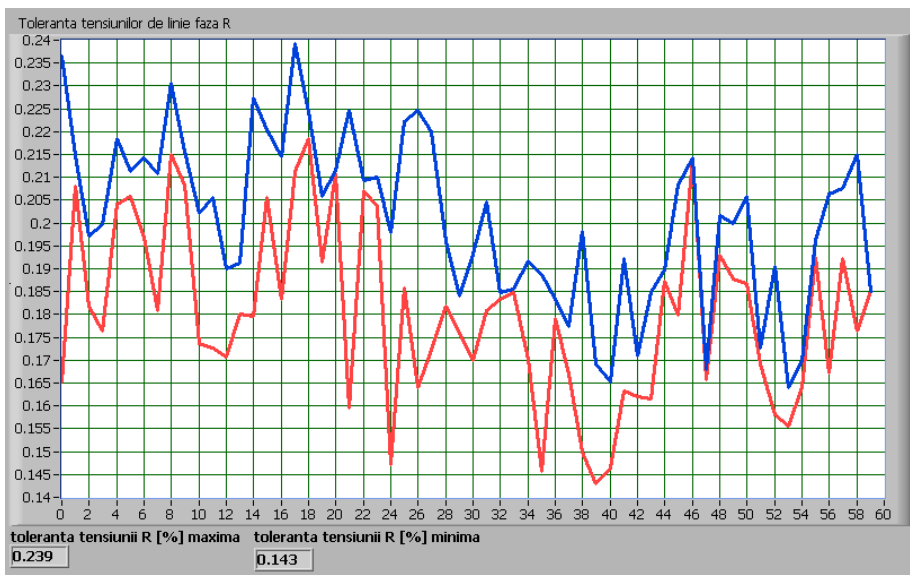
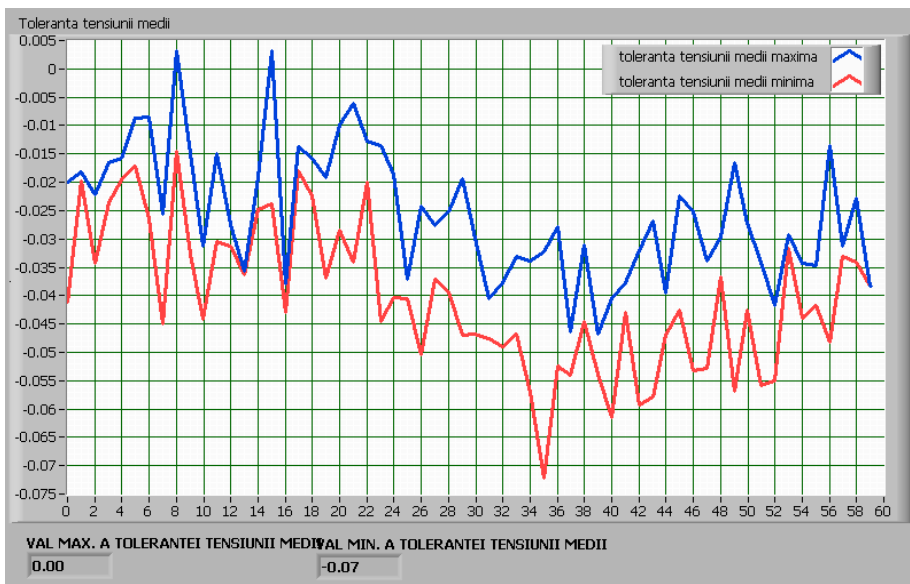
- [8] Riccardo Marino, Patrizio Tomei, *Robust Adaptive State-Feedback Tracking for Nonlinear Systems*, IEEE Transactions on Automatic Control, vol.43, no.1, 1998
- [9] *SimDriveline for use with Simulink*, MathWorks 2005
- [10] J. Arrillaga, N.R. Watson, *Computer Modelling of Electrical Power Systems*, John Wiley&Sons, 2001

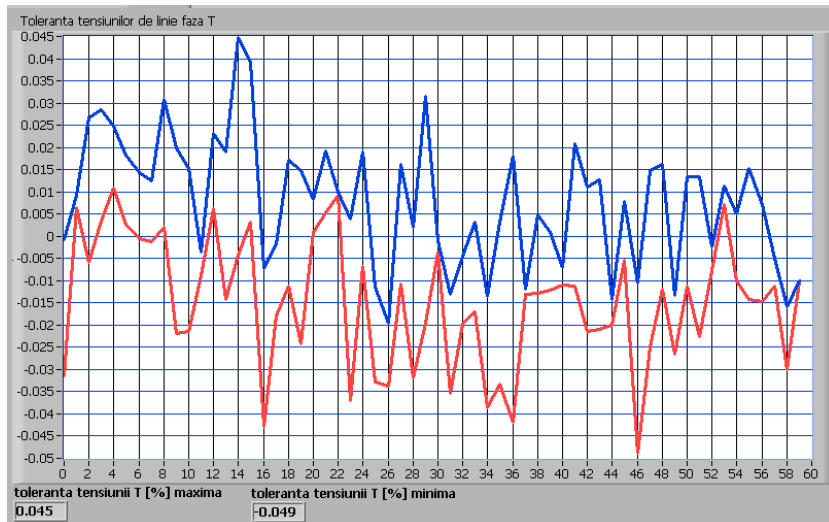
Table 1: PARAMETERS OF POWER STATION

No parameter	Physical quantity	Values as per STANAG 1008			RECORDS					
		Disruptive factors			CONVERTER 1			CONVERTER 2		
		ext.	int.	cum	Phases			Phases		
					RS	ST	TR	RS	ST	TR
1	2	3	4	5	6	7	8	9	10	11
1	Nominal Voltage	447V (voltage adjusted in order to recover voltage drops on JT connector)								
1.1	Mean Stress Variation [%]	± 5		± 6	0.00			0.52		
					-0.07			-0.08		
1.2	Circuit Voltage Variation + 1.3 [%]	± 7		± 8	0.239	-0.237	0.045	0.511	0.495	0.562
					0.143	-0.339	-0.049	-0.167	0.036	-0.116
1.3	Circuit Voltage Unbalance Variation [%]		2		0.003			0.001		
1.4	Voltage Modulation		2 %		0.04	0.05	0.03	0.03	0.03	0.03
1.5	Voltage Transitory Variation [%]		± 16		condition that was automatically met since the domain was not exceeded ± 16%			condition that was automatically met since the domain was not exceeded ± 16%		
1.6	Recovery Time [s]		2 s		condition that was automatically met since the domain was not exceeded ± 16%			condition that was automatically met since the domain was not exceeded ± 16%		
1.7	Voltage Peak [kV]		2KV		<2 KV no voltage peaks during the defined period of time of <1ms			<2 KV no voltage peaks during the defined period of time of <1ms		
2	Waveform									
2.1	Total Harmonic Distortion [%]		5		1.303	1.421	1.330	1.274	1.352	1.325
2.2	Individual Harmonic [%]		3		1.181	1.252	1.160	1.162	1.215	1.173
2.3	Deviation Factor [%]		5		4.747	4.87	5.14	4.404	4.59	4.16
3	Frequency	60 Hz								

3.1	Frequency Variation [%]	± 3		± 5.5	0.017	0.064
					0.017	0.052
3.2	Frequency Modulation [%]		0.5		0.003	0.015
3.3	Frequency Transitory Variation [%]		± 4	± 5,5	condition that was automatically met since the domain was not exceeded 4%	condition that was automatically met since the domain was not exceeded 4%
3.4	Recovery Time [s]		2 s		condition that was automatically met since the domain was not exceeded 4%	<2 s. condition that was automatically met since the domain was not exceeded ± 4%

Annex 1
 Quality parameters according STANAG 1008
 Converter 1, acquisition time 60 minute





Annex 2
 Quality parameters, 440V, 60 Hz according STANAG 1008
 Converter 1, acquisition time 24 minute

